

# **NUC029xAN Board Support Package Directory Introduction**

Rev 3.00.005

## Directory Information

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|-------------------|---|
| <b>Document</b>   | Driver reference manual and revision history. |
| <b>Library</b>    | Driver header and source files.               |
| <b>SampleCode</b> | Driver sample code.                           |

## Document Information

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| <b>BSP Revision History</b>   | Show all the revision history about specific BSP.      |
| <b>Driver Reference Guide</b> | Describe the definition, input and output of each API. |

## Library Information

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| <b>CMSIS</b>     | CMSIS definitions by ARM® Corp.                |
| <b>Device</b>    | CMSIS compliant device header file.            |
| <b>StdDriver</b> | All peripheral driver header and source files. |

## Sample Code Information

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| <b>\SampleCode\Hard_Fault_Sample</b> | Show hard fault information when hard fault happened.           |
| <b>\SampleCode\ISP</b>               | Sample codes for In-System-Programming.                         |
| <b>\SampleCode\Template</b>          | Software Development Template.                                  |
| <b>\SampleCode\Semihost</b>          | A sample code to show how to debug with semihost message print. |
| <b>\SampleCode\RegBased</b>          | The sample codes which access control registers directly.       |
| <b>\SampleCode\StdDriver</b>         | NUC029xAN Driver Samples  |

**\SampleCode\ISP**

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| <b>ISP_I2C</b>   | In-System-Programming Sample code through I2C interface.   |
| <b>ISP_RS485</b> | In-System-Programming Sample code through RS485 interface. |
| <b>ISP_SPI</b>   | In-System-Programming Sample code through SPI interface.   |
| <b>ISP_UART</b>  | In-System-Programming Sample code through UART interface.  |

## \SampleCode\RegBased

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|--------------------------------|--|
| <b>ACMP</b>                    | Demonstrate how ACMP <sup>[1]</sup> works with internal band-gap voltage.  |
| <b>ADC_BurstMode</b>           | Demonstrate A/D conversion with burst mode. In burst mode, ADC will sample and convert a specified channel continuously and store the conversion result in FIFO buffers. |
| <b>ADC_ContinuousScanMode</b>  | Demonstrate how to use continuous scan mode and finishes two cycles of conversion for the specified channels.  |
| <b>ADC_PwmTrigger</b>          | Demonstrate how to trigger ADC by PWM.   |
| <b>ADC_ResultMonitor</b>       | Demonstrate how to use the digital compare function to monitor the conversion result of channel 2.   |
| <b>ADC_SingleCycleScanMode</b> | Demonstrate how to use single cycle scan mode and finishes one cycle of conversion for the specified channels.   |
| <b>ADC_SingleMode</b>          | Demonstrate how to use single mode and finishes the conversion of the specified channel.   |
| <b>EBI_NOR</b>                 | Demonstrate how to read/program external NOR Flash device (W39L040P) through EBI bus.  |
| <b>EBI_SRAM</b>                | Demonstrate how to read/program external SRAM device (BS616LV4017) through EBI bus.  |
| <b>FMC_IAP</b>                 | Demonstrate how to call LDROM functions from APROM. The code in APROM will look up the table at 0x100E00 to get the address of function of LDROM and call the function.  |
| <b>FMC_RW</b>                  | Demonstrate how to read/program embedded flash by ISP function.  |
| <b>GPIO_EINTAndDebounce</b>    | Demonstrate how to use GPIO external interrupt function and de-bounce function.  |
| <b>GPIO_INT</b>                | Demonstrate how to use GPIO interrupt function.  |
| <b>GPIO_OutputInput</b>        | Demonstrate how to set GPIO pin mode and use pin data input/output control.  |

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| <b>GPIO_PowerDown</b>     | Demonstrate how to wake-up form Power-down mode by GPIO interrupt.   |
| <b>HDIV</b>               | Demonstrate how to user divider API and how to use hardware divider by control registers.  |
| <b>I2C_EEPROM</b>         | Demonstrate how to access EEPROM by I <sup>2</sup> C interface.  |
| <b>I2C_GCMode_MASTER</b>  | Demonstrate how a Master uses I <sup>2</sup> C address 0x0 to write data to I <sup>2</sup> C Slave. Needs to work with I2C_GCMode_SLAVE sample code. |
| <b>I2C_GCMode_SLAVE</b>   | Demonstrate how to receive Master data in GC (General Call) mode. Needs to work with I2C_GCMode_MASTER sample code.                                  |
| <b>I2C_MASTER</b>         | Demonstrate how a Master access Slave. Needs to work with I2C_SLAVE sample code.   |
| <b>I2C_SLAVE</b>          | Demonstrate how to set I <sup>2</sup> C in slave mode to receive the data of a Master. Needs to work with I2C_MASTER sample code.                    |
| <b>I2C_Wakeup_Master</b>  | Demonstrate how to wake-up MCU from power-down. Needs to work with I2C_Wakeup_Slave sample code.   |
| <b>I2C_Wakeup_Slave</b>   | Demonstrate how to set I <sup>2</sup> C to wake-up MCU from power-down mode. Needs to work with I2C_Wakeup_Master sample code.                       |
| <b>PWM</b>                | Demonstrate how to use PWM to generate different frequency (Tenor C Do ~ Si) waveform.   |
| <b>PWM_Capture</b>        | Demonstrate how to use PWMB Channel 2 captures PWMB Channel 1 Waveform.  |
| <b>PWM_DeadZone</b>       | Demonstrate how to use PWM Dead Zone function.   |
| <b>PWM_DoubleBuffer</b>   | Use PWM Double Buffer function to change duty cycle and period of output waveform.   |
| <b>SPI_LoopBackTest</b>   | Demonstrate the data transfer between a SPI master and a SPI slave.  |
| <b>SPI_MasterFifoMode</b> | Demonstrate how to communicate with an off-chip SPI slave  |

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|                             | device with FIFO mode. This sample code needs to work with SPI_SlaveFifoMode sample code.   |
| <b>SPI_SlaveFifoMode</b>    | Demonstrate how to communicate with an off-chip SPI master device with FIFO mode. This sample code needs to work with SPI_MasterFifoMode sample code. |
| <b>SYS</b>                  | Demonstrate how to change system clock to different PLL frequency and output system clock from CLK0 pin.  |
| <b>TIMER_Capture</b>        | Demonstrate how to use timer2 capture event to capture timer2 counter value.  |
| <b>TIMER_Counter</b>        | Demonstrate how to use timer1 counter input function to count the input event.  |
| <b>TIMER_PeriodicINT</b>    | Demonstrate how to perform timer counting in periodic mode.   |
| <b>TIMER_PowerDown</b>      | Demonstrate how to use timer0 toggle-output interrupt event to wake-up system.  |
| <b>UART_AutoFlow_Master</b> | Demonstrate how to transmit and receive data with auto flow control. The sample code needs to work with UART_AutoFlow_Slave.                          |
| <b>UART_AutoFlow_Slave</b>  | Demonstrate how to transmit and receive data with auto flow control. The sample code needs to work with UART_AutoFlow_Master.                         |
| <b>UART_IrDA_Master</b>     | Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with UART_IrDA_Slave.                                   |
| <b>UART_IrDA_Slave</b>      | Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with UART_IrDA_Master.                                  |
| <b>UART_LIN</b>             | Demonstrate how to transmit LIN header and response.  |
| <b>UART_RS485_Master</b>    | Demonstrate how to transmit and receive data in UART RS485 mode. The sample code needs to work with UART_RS485_Slave.                                 |
| <b>UART_RS485_Slave</b>     | Demonstrate how to transmit and receive data in UART RS485  |

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|                           | mode. The sample code needs to work with UART_RS485_Master.   |
| <b>UART_TxRx_Function</b> | Demonstrate how UART transmit and receive data from PC terminal through RS232 interface.                |
| <b>UART_Wakeup</b>        | Show how to wake up system form Power-down mode by UART interrupt.                                      |
| <b>WDT_PowerDown</b>      | Demonstrate how to use WDT time-out interrupt event to wake-up system.                                  |
| <b>WDT_TimeoutINT</b>     | Select one WDT time-out interval period time to generate time-out interrupt event.                      |
| <b>WDT_TimeoutReset</b>   | Demonstrate how to cause WDT time-out reset system event while WDT time-out reset delay period expired. |
| <b>WWDT_CompareINT</b>    | Select one WWDT window compare value to generate window compare match interrupt event.                  |

1. Analog Comparator (ACMP).

### **\SampleCode\StdDriver**

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|--------------------------------|--|
| <b>ACMP</b>                    | Demonstrate how ACMP works with internal band-gap voltage.   |
| <b>ADC_BurstMode</b>           | Demonstrate A/D conversion with burst mode. In burst mode, ADC will sample and convert a specified channel continuously and store the conversion result in FIFO buffers. |
| <b>ADC_ContinuousScanMode</b>  | Demonstrate how to use continuous scan mode and finishes two cycles of conversion for the specified channels.  |
| <b>ADC_PwmTrigger</b>          | Demonstrate how to trigger ADC by PWM.   |
| <b>ADC_ResultMonitor</b>       | Demonstrate how to use the digital compare function to monitor the conversion result of channel 2.   |
| <b>ADC_SingleCycleScanMode</b> | Demonstrate how to use single cycle scan mode and finishes   |



|                                |  |
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|                                | one cycle of conversion for the specified channels.  |
| <b>ADC_SingleMode</b>          | Demonstrate how to use single mode and finishes the conversion of the specified channel.                                     |
| <b>CAN_BasicMode_Receive</b>   | Demonstrate how to receive message in Basic mode. The sample code needs to work with CAN_BasicMode_Transmit.                 |
| <b>CAN_BasicMode_Transmit</b>  | Demonstrate how to transmit message in Basic mode. The sample code needs to work with CAN_BasicMode_Receive.                 |
| <b>CAN_NormalMode_Receive</b>  | Demonstrate how to receive message in Normal mode. The sample code needs to work with CAN_NormalMode_Transmit.               |
| <b>CAN_NormalMode_Transmit</b> | Demonstrate how to transmit message in Normal mode. The sample code needs to work with CAN_NormalMode_Receive.               |
| <b>FMC</b>                     | Demonstrate how to access embedded flash and switching between APROM and LDROM.  |
| <b>FMC_IAP</b>                 | Demonstrate how to reboot to LDROM functions from APROM. This sample code set VECMAP to LDROM and reset to re-boot to LDROM. |
| <b>FMC_RW</b>                  | Demonstrate how to read/program embedded flash by ISP function.  |
| <b>FMC_MultiBoot</b>           | Demonstrate how to implement multi-boot system to boot from different applications in APROM.                                 |
| <b>GPIO_EINTAndDebounce</b>    | Demonstrate how to use GPIO external interrupt function and de-bounce function.  |
| <b>GPIO_INT</b>                | Demonstrate how to use GPIO interrupt function.  |
| <b>GPIO_OutputInput</b>        | Demonstrate how to set GPIO pin mode and use pin data input/output control.  |
| <b>GPIO_PowerDown</b>          | Demonstrate how to wake-up form Power-down mode by GPIO interrupt.   |
| <b>HDIV</b>                    | Demonstrate how to user divider API and how to use   |

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|                          | hardware divider by control registers.   |
| <b>I2C_EEPROM</b>        | Demonstrate how to access EEPROM by I <sup>2</sup> C interface.  |
| <b>I2C_GCMode_MASTER</b> | Demonstrate how a Master uses I <sup>2</sup> C address 0x0 to write data to I <sup>2</sup> C Slave. Needs to work with I2C_GCMode_SLAVE sample code. |
| <b>I2C_GCMode_SLAVE</b>  | Demonstrate how to receive Master data in GC (General Call) mode. Needs to work with I2C_GCMode_MASTER sample code.                                  |
| <b>I2C_MASTER</b>        | Demonstrate how a Master access Slave. Needs to work with I2C_SLAVE sample code.   |
| <b>I2C_SLAVE</b>         | Demonstrate how to set I <sup>2</sup> C in slave mode to receive the data of a Master. Needs to work with I2C_MASTER sample code.                    |
| <b>I2C_Wakeup_Master</b> | Demonstrate how to wake-up MCU from power-down. Needs to work with I2C_Wakeup_Slave sample code.   |
| <b>I2C_Wakeup_Slave</b>  | Demonstrate how to set I <sup>2</sup> C to wake-up MCU from power-down mode. Needs to work with I2C_Wakeup_Master sample code.                       |
| <b>PWM_Capture</b>       | Demonstrate how to use PWMB Channel 2 captures PWMB Channel 1 Waveform.  |
| <b>PWM_DeadZone</b>      | Demonstrate how to use PWM Dead Zone function.   |
| <b>PWM_DoubleBuffer</b>  | Use PWM Double Buffer function to change duty cycle and period of output waveform.   |
| <b>SPI_LoopBackTest</b>  | Demonstrates the data transfer in SPI master mode.   |
| <b>SYS</b>               | Demonstrate how to change system clock to different PLL frequency and output system clock from CLK0 pin.   |
| <b>TIMER_Capture</b>     | Demonstrate how to use timer2 capture event to capture timer2 counter value.   |
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| <b>TIMER_PeriodicINT</b>    | Demonstrate how to perform timer counting in periodic mode.   |
| <b>TIMER_PowerDown</b>      | Demonstrate how to use timer0 toggle-output interrupt event to wake-up system.  |
| <b>UART_Autoflow_Master</b> | Demonstrate how to transmit and receive data with auto flow control. The sample code needs to work with UART_Autoflow_Slave.  |
| <b>UART_Autoflow_Slave</b>  | Demonstrate how to transmit and receive data with auto flow control. The sample code needs to work with UART_Autoflow_Master. |
| <b>UART_IrDA_Master</b>     | Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with UART_IrDA_Slave.           |
| <b>UART_IrDA_Slave</b>      | Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with UART_IrDA_Master.          |
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|                         |   |
|-------------------------|---|
| <b>WDT_TimeoutReset</b> | Demonstrate how to cause WDT time-out reset system event while WDT time-out reset delay period expired. |
| <b>WWDT_CompareINT</b>  | Select one WWDT window compare value to generate window compare match interrupt event.                  |

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